Editorial

Optimal Control Theory: Introduction to the Special Issue

Ellina Grigorieva

Department of Mathematics and Computer Science, Texas Woman's University, Denton, TX 76204, USA; egrigorieva@mail.twu.edu

Optimal control theory is a modern extension of the classical calculus of variations. Converting a calculus of variation problem into an optimal control problem requires one more conceptual extension—the addition of control variables to state equations. While the main result of the calculus of variations was the Euler equation, the Pontryagin maximum principle is the main result of optimal control theory. The maximum principle was developed by a group of Russian mathematicians in the 1950s and gives the necessary conditions for optimality in a wide range of dynamic optimization problems. At present, for deterministic control models described by ordinary differential equations, the Pontryagin maximum principle is used as often as Bellman's dynamic programming method.

An optimal control problem includes a calculation of the optimal control and the synthesis of the optimal control system. Optimal control, as a rule, is calculated by numerical methods for finding the extremum of an objective function or by solving a two-point boundary value problem for a system of differential equations. The synthesis of optimal control from a mathematical point of view is a nonlinear programming problem in function spaces.

This Special Issue gathers research focused on the development of novel analytical and numerical methods for solutions of optimal control or of dynamic optimization problems, including changing and incomplete information about the investigated objects, application to medicine, infectious diseases, and economic or physical phenomena. Investigations of new classes of optimization problems, optimal control of nonlinear systems, as well as the task of reconstructing input signals are also presented. For example, the articles that develop new algorithms to implement some of the principles of regularization using constructive iterative procedures or papers that create an optimal control model which can accumulate experience and improve its work on this basis (the so-called learning optimal control system) are given. Finally, the applied articles focused on control models of economic, physical, medical or environmental processes or resource allocation on the specified time interval or on the infinite planning horizon are presented also.

The original research articles of this issue reflect new advances in optimal control and differential games; deterministic and stochastic control processes; combined methods of synthesis of both deterministic and stochastic systems with full information about parameters, states and perturbations. This issue collects the papers that allow the use of analytical methods to study the various problems of optimal control and its evaluation, as well as applications of optimal controls and differential games to describe complex nonlinear phenomena.

A short summary of all the manuscripts placed in an alphabetical order of the first authors is given below.

Within the framework of the above, Arias-Castro, Martinez-Romero and Vasilieva [1] focus on the design and analysis of short-term control intervention measures seeking to suppress local populations of Aedes aegypti mosquitoes, the major transmitters of dengue and other vector-borne infections. In addition to traditional measures involving the spraying of larvicides and/or insecticides, a biological control based on the deliberate introduction of predacious species feeding on the aquatic stages of mosquitoes is included. From a methodological standpoint, such a study relies on the application of the optimal control modeling framework in combination with cost-effectiveness analysis. This approach not only enables the design of optimal strategies for external control intervention

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Optimal Control Theory Suresh P. Sethi,Gerald L. Thompson,2005-09-06 Optimal control methods are used to determine optimal ways to control a dynamic system The theoretical work in this field serves as a foundation for the book which the authors have applied to business management problems developed from their research and classroom instruction Sethi and Thompson have provided management science and economics communities with a thoroughly revised edition of their classic text on Optimal Control Theory The new edition has been completely refined with careful attention to the text and graphic material presentation Chapters cover a range of topics including finance production and inventory problems marketing problems machine maintenance and replacement problems of optimal consumption of natural resources and applications of control theory to economics The book contains new results that were not available when the first edition was published as well as an expansion of the material on stochastic optimal control theory   **Optimal Control Theory** Donald E. Kirk,2012-04-26 Upper level undergraduate text introduces aspects of optimal control theory dynamic programming Pontryagin s minimum principle and numerical techniques for trajectory optimization Numerous figures tables Solution guide available upon request 1970 edition   **Solutions Manual for Optimal Control Theory** Suresh P. Sethi,Gerald L. Thompson,1981-11-30   **Solutions Manual for Optimal Control Theory** Suresh Prakash Sethi,Gerald L Thompson,2014-01-15   Calculus of Variations and Optimal Control Theory Daniel Liberzon,2011-12-19 This textbook offers a concise yet rigorous introduction to calculus of variations and optimal control theory and is a self contained resource for graduate students in engineering applied mathematics and related subjects Designed specifically for a one semester course the book begins with calculus of variations preparing the ground for optimal control It then gives a complete proof of the maximum principle and covers key topics such as the Hamilton Jacobi Bellman theory of dynamic programming and linear quadratic optimal control Calculus of Variations and Optimal Control Theory also traces the historical development of the subject and features numerous exercises notes and references at the end of each chapter and suggestions for further study Offers a concise yet rigorous introduction Requires limited background in control theory or advanced mathematics Provides a complete proof of the maximum principle Uses consistent notation in the exposition of classical and modern topics Traces the historical development of the subject Solutions manual available only to teachers Leading universities that have adopted this book include University of Illinois at Urbana Champaign ECE 553 Optimum Control Systems Georgia Institute of Technology ECE 6553 Optimal Control and Optimization University of Pennsylvania ESE 680 Optimal Control Theory University of Notre Dame EE 60565 Optimal Control   *Modern Control System Theory and Design* Stanley M. Shinners,1998-05-06 The definitive guide to control system design Modern Control System Theory and Design Second Edition offers themost comprehensive treatment of control systems available today Its unique text software combination integrates classical andmodern control system theories while promoting an interactive computer based approach to design

solutions The sheer volume ofpractical examples as well as the hundreds of illustrations ofcontrol systems from all engineering fields make this volumeaccessible to students and indispensable for professionalengineers This fully updated Second Edition features a new chapter on moderncontrol system design including state space design techniques Ackermann s formula for pole placement estimation robust control and the H method for control system design Other notable additionsto this edition are Free MATLAB software containing problem solutions which can beretrieved from The Mathworks Inc anonymous FTP server atftp ftp mathworks com pub books shinners Programs and tutorials on the use of MATLAB incorporated directlyinto the text A complete set of working digital computer programs Reviews of commercial software packages for control systemanalysis An extensive set of new worked out illustrative solutions addedin dedicated sections at the end of chapters Expanded end of chapter problems one third with answers tofacilitate self study An updated solutions manual containing solutions to the remainingtwo thirds of the problems Superbly organized and easy to use Modern Control System Theoryand Design Second Edition is an ideal textbook for introductorycourses in control systems and an excellent professional reference Its interdisciplinary approach makes it invaluable for practicingengineers in electrical mechanical aeronautical chemical andnuclear engineering and related areas *Scientific and Technical Aerospace Reports* ,1970

Calculus of Variations and Optimal Control Theory - A Concise Introduction Instructor's Manual Daniel Liberzon,2012-01-01 This textbook offers a concise yet rigorous introduction to calculus of variations and optimal control theory and is a self contained resource for graduate students in engineering applied mathematics and related subjects Designed specifically for a one semester course the book begins with calculus of variations preparing the ground for optimal control It then gives a complete proof of the maximum principle and covers key topics such as the Hamilton Jacobi Bellman theory of dynamic programming and linear quadratic optimal control Calculus of Variations and Optimal Control Theory also traces the historical development of the subject and features numerous exercises notes and references at the end of each chapter and suggestions for further study Offers a concise yet rigorous introduction Requires limited background in control theory or advanced mathematics Provides a complete proof of the maximum principle Uses consistent notation in the exposition of classical and modern topics Traces the historical development of the subject Solutions manual available only to teachers Leading universities that have adopted this book include University of Illinois at Urbana Champaign ECE 553 Optimum Control Systems Georgia Institute of Technology ECE 6553 Optimal Control and Optimization University of Pennsylvania ESE 680 Optimal Control Theory University of Notre Dame EE 60565 Optimal Control **Control Theory for Humans** Richard J. Jagacinski,John M. Flach,2018-10-08 This textbook provides a tutorial introduction to behavioral applications of control theory Control theory describes the information one should be sensitive to and the pattern of influence that one should exert on a dynamic system in order to achieve a goal As such it is applicable to various forms of dynamic behavior The book primarily deals with manual control e g moving the cursor on a computer screen lifting an object hitting a

ball driving a car both as a substantive area of study and as a useful perspective for approaching control theory It is the experience of the authors that by imagining themselves as part of a manual control system students are better able to learn numerous concepts in this field Topics include varieties of control theory such as classical optimal fuzzy adaptive and learning control as well as perception and decision making in dynamic contexts The authors also discuss implications of control theory for how experiments can be conducted in the behavioral sciences In each of these areas they have provided brief essays intended to convey key concepts that enable the reader to more easily pursue additional readings Behavioral scientists teaching control courses will be very interested in this book *Scientific and Technical Books in Print* ,1972

Engineering Vibration Analysis with Application to Control Systems C. Beards,1995-06-17 Most machines and structures are required to operate with low levels of vibration as smooth running leads to reduced stresses and fatigue and little noise This book provides a thorough explanation of the principles and methods used to analyse the vibrations of engineering systems combined with a description of how these techniques and results can be applied to the study of control system dynamics Numerous worked examples are included as well as problems with worked solutions and particular attention is paid to the mathematical modelling of dynamic systems and the derivation of the equations of motion All engineers practising and student should have a good understanding of the methods of analysis available for predicting the vibration response of a system and how it can be modified to produce acceptable results This text provides an invaluable insight into both **Optimal Control Engineering with MATLAB** Rami A. Maher,2017 A solution manual of the 110 questions that were presented in the author s previous book Optimal control engineering with MATLAB Technical Bulletin ,1938 Solutions Manual for Optimal Control Systems Laurie Kelly,2004-02 *Advanced Modern Control System Theory and Design* Stanley M. Shinners,1998-09-30 Linear Control System Compensation and Design Modern Control System Design Using State Space Pole Placement Ackermann s Formula Estimation Robust Control and H8 Techniques Digital Control System Analysis and Design Nonlinear Control System Design Introduction to Optimal Control Theory and Its Applications Control System Design Examples Complete Case Studies **Servomechanisms: Bulletin of Automatic and Manual Control Abstracts** ,1965 Journal of Guidance, Control, and Dynamics ,2008 **International Journal of Electrical Engineering Education** ,1983 **Control Theory and Advanced Technology** ,1995 *Standard Handbook for Aerospace Engineers, Second Edition* Brij N. Agrawal,Max F. Platzer,2018-02-26 Publisher s Note Products purchased from Third Party sellers are not guaranteed by the publisher for quality authenticity or access to any online entitlements included with the product A single source of essential information for aerospace engineers This fully revised resource presents theories and practices from more than 50 specialists in the many sub disciplines of aeronautical and astronautical engineering all under one cover The Standard Handbook for Aerospace Engineers Second Edition contains complete details on classic designs as well as the latest techniques materials and processes used in aviation defense and space systems You

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