

B-2-22.

$$\ddot{x} + 4x = 0, \quad x(0) = 5, \quad \dot{x}(0) = 0$$

The Laplace transform of the given differential equation is

$$(s^2X(s) - sx(0) - \dot{x}(0)) + 4X(s) = 0$$

Substitution of the initial conditions into this last equation gives

$$(s^2 + 4)X(s) = 5s$$

Solving for $X(s)$, we obtain

$$X(s) = \frac{5s}{s^2 + 4}$$

The inverse Laplace transform of $X(s)$ is

$$x(t) = 5 \cos 2t$$

This is the solution of the given differential equation.

B-2-23.

$$\ddot{x} + \omega_n^2 x = t, \quad x(0) = 0, \quad \dot{x}(0) = 0$$

The Laplace transform of this differential equation is

$$s^2X(s) + \omega_n^2X(s) = \frac{1}{s}$$

Solving this equation for $X(s)$, we obtain

$$X(s) = \frac{1}{s^2(s^2 + \omega_n^2)} = \left(\frac{1}{s^2} - \frac{1}{s^2 + \omega_n^2} \right) \frac{1}{\omega_n^2}$$

The inverse Laplace transform of $X(s)$ is

$$x(t) = \frac{1}{\omega_n^2} (t - \frac{1}{\omega_n} \sin \omega_n t)$$

This is the solution of the given differential equation.

B-2-24.

$$2\ddot{x} + 2\dot{x} + x = 1, \quad x(0) = 0, \quad \dot{x}(0) = 2$$

The Laplace transform of this differential equation is

$$2(s^2X(s) - sx(0) - \dot{x}(0)) + 2(sX(s) - x(0)) + X(s) = \frac{1}{s}$$

System Dynamics Solution Manual Ch 7

**James N. Spencer, George M.
Bodner, Lyman H. Rickard**

System Dynamics Solution Manual Ch 7:

System Dynamics for Engineering Students Nicolae Lobontiu,2010-03-19 System Dynamics for Engineering Students Concepts and Applications discusses the basic concepts of engineering system dynamics Engineering system dynamics focus on deriving mathematical models based on simplified physical representations of actual systems such as mechanical electrical fluid or thermal and on solving the mathematical models The resulting solution is utilized in design or analysis before producing and testing the actual system The book discusses the main aspects of a system dynamics course for engineering students mechanical electrical and fluid and thermal system modeling the Laplace transform technique and the transfer function approach It also covers the state space modeling and solution approach modeling system dynamics in the frequency domain using the sinusoidal harmonic transfer function and coupled field dynamic systems The book is designed to be a one semester system dynamics text for upper level undergraduate students with an emphasis on mechanical aerospace or electrical engineering It is also useful for understanding the design and development of micro and macro scale structures electric and fluidic systems with an introduction to transduction and numerous simulations using MATLAB and SIMULINK

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attitude of the body is under consideration a rigid body model should be adopted If deformation is a concern a model of deformable body should be applied Consequently a book in mechanics for engineers should encompass a variety of models of the body ranging from particles to continua such as solids or fluids This book also meets that need **Local Applications of the Ecological Approach To Human-Machine Systems** Peter A. Hancock, John M. Flach, Jeff Caird, Kim J. Vicente, 2018-05-02

There is a growing consensus in the human factors ergonomics community that human factors research has had little impact on significant applied problems Some have suggested that the problem lies in the fact that much HF E research has been based on the wrong type of psychology an information processing view of psychology that is reductionistic and context free Ecological psychology offers a viable alternative presenting a richer view of human behavior that is holistic and contextualized The papers presented in these two volumes show the conceptual impact that ecological psychology can have on HF E as well as presenting a number of specific examples illustrating the ecological approach to human machine systems It is the first collection of papers that explicitly draws a connection between these two fields While work in this area is only just beginning the evidence available suggests that taking an ecological approach to human factors ergonomics helps bridge the existing gap between basic research and applied problems

Modeling for Reliability Analysis Jan Pukite, Paul Pukite, 1998-06-22 Markov modeling has long been accepted as a fundamental and powerful technique for the fault tolerance analysis of mission critical applications However the elaborate computations required have often made Markov modeling too time consuming to be of practical use on these complex systems With this hands on tool designers can use the Markov modeling technique to analyze safety reliability maintainability and cost effectiveness factors in the full range of complex systems in use today Featuring ground breaking simulation software and a comprehensive reference manual MARKOV MODELING FOR RELIABILITY ANALYSIS helps system designers surmount the mathematical computations that have previously prevented effective reliability analysis The text and software compose a valuable self study tool that is complete with detailed explanations examples and a library of Markov models that can be used for experiments and as derivations for new simulation models The book details how these analyses are conducted while providing hands on instruction on how to develop reliability models for the full range of system configurations Computer Aided Rate Modeling and Simulation CARMS software is an integrated modeling tool that includes a diagram based environment for model setup a spreadsheet like interface for data entry an expert system link for automatic model construction and an interactive graphic interface for displaying simulation results

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